# Representations, isomorphism

Lecture 2



## More definitions and examples

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The **order** of *G* is |V(G)|, i.e. the number of vertices, the size of *G* is |E(G)|, the number of edges.

The **open neighborhood** of *v*, denoted N(v) or  $N_G(v)$  is the set of vertices adjacent to *v*, and the **closed neighborhood** of *v*, denoted N[v] or  $N_G[v]$  is given by  $N[v] = N(v) \cup \{v\}$ .

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The **degree** of a vertex  $v \in V(G)$  will be denoted by d(v) or  $d_G(v)$  (when *G* is not clear from context). The **maximum degree** of *G* is  $\Delta(G) = \max\{d(v) \mid v \in V(G)\}$ . Similarly the **minimum degree** of *G* is  $\delta(G) = \min\{d(v) \mid v \in V(G)\}$ .

We say *G* is *k*-regular if every vertex has degree *k*.

# Ways to represent graphs

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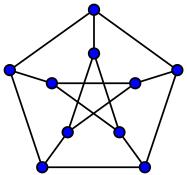
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(b) Set a rule. Example 1:
The vertex set of Petersen graph P is
\{(i,j) : 1 \le i < j \le 5\} and vertices (i,j) and (k, l) are adjacent
iff \{i,j\} \cap \{k,l\} = \emptyset.
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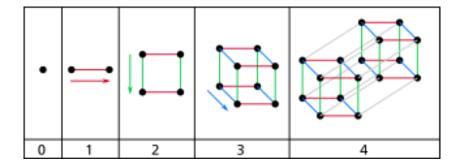
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#### Example 2:

The vertex set of the *k*-dimensional cube  $Q_k$  is  $V_k = \{(a_1, \ldots, a_k) : a_i \in \{0, 1\}\}$  and two vectors in  $V_k$  are adjacent iff they differ in exactly one coordinate.

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(d) Incidence matrices. Given a loopless graph *G* with vertex set  $\{v_1, \ldots, v_n\}$  and edge set  $\{e_1, \ldots, e_m\}$ , the incidence matrix M(G) of *G* is the  $n \times m$  matrix  $\{m_{i,j}\}_{1 \le i \le n, 1 \le j \le m}$  where  $m_{i,j}$  is 1 if  $v_i$  is an end of  $e_i$  and 0 otherwise.

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(e) Lists of neighbors. Given a simple graph *G* with vertex set  $\{v_1, \ldots, v_n\}$ , for every  $v_i$  the list of its neighbors is given.

# Graph isomorphism

An isomorphism from a simple graph *G* to a simple graph *H* is a bijection  $f : V(G) \rightarrow V(H)$  s.t.  $uv \in E(G)$  if and only if  $f(u)f(v) \in E(H)$ .

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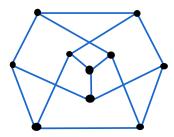
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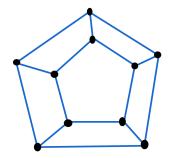
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Two graphs G and H are isomorphic if there is an isomorphism from G to H.

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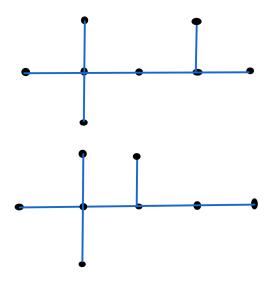
#### Isomorphism, Example 1:





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#### Isomorphism, Example 2:



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## Walks

A walk in a graph *G* is a list  $v_0, e_1, v_1, e_2, v_2, \ldots, e_\ell, v_\ell$  of vertices  $v_i$  and edges  $e_i$  such that for each  $1 \le i \le \ell$ , the endpoints of  $e_i$  are  $v_{i-1}$  and  $v_i$ .

If the first vertex of a walk is u and the last vertex on the walk is v, we call this a u, v-walk. When G is a simple graph, we also may specify a walk by simply listing the vertices, since it is unambiguous which edge is traversed in each step.

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A *u*, *v*-trail is a *u*, *v*-walk with no repeated edges (but vertices may repeat). If  $u \neq v$ , a *u*, *v*-path is a *u*, *v*-walk with no repeated vertices.

(You should convince yourself that the subgraph definition of a path matches up with the walk definition of a path).

If u = v, then we call a u, v-walk or trail **closed**. The **length** of a walk, trail or path is the number of edges traversed.